

Introduction to Parallel Computing

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NASA
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Computing

✦ Computation

What is the purpose of a Computer?

To Compute FAST

What Limits the speed of a computer?

Component Speed (gates)

Distance between components (speed of light)

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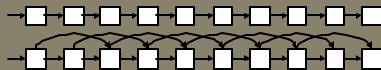
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Parallel Programming

How do you design a parallel program?

Parallel programming is NOT the dividing up
of a serial program

For example, find the end of a list:



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Essential aspects of Parallel Programming

✦ Computation

✦ Communication

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Simple Parallelism

- ✦ Mandelbrot set
- ✦ SETI online
- ✦ Ensembles
 - ✦ Climate model
 - ✦ Solar atmosphere
- ✦ The Web
- ✦ Data grid

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Complex Parallel

- ✦ Image generation
- ✦ Unstructured Grid computations
- ✦ Rectangular Grid computations
- ✦ Image and signal processing
- ✦ FFT – Fast Fourier Transforms
- ✦ Cellular Automata

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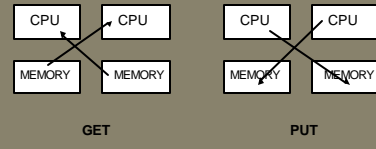
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Communication

- ✦ Get/Put
- ✦ Send/Receive
- ✦ Scatter/Gather
- ✦ All to All
- ✦ Broadcast/Reduction
- ✦ Scan

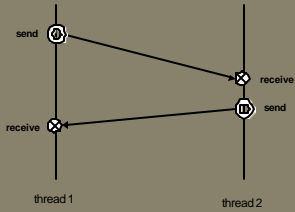
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Get / Put



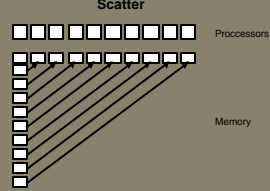
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Send / Receive



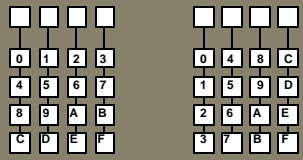
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Scatter / Gather



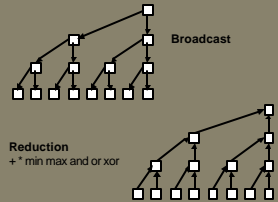
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All to All



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Broadcast / Reduction



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Scan

Scan add

Scan xor

1	1	1	0	1	0	1	1
1	2	3	3	4	4	5	6

1	1	1	0	1	0	1	1
1	0	1	1	0	0	1	0

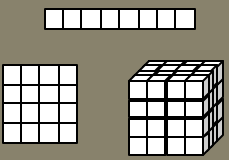
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Topologies

- ◆ Arrays
- ◆ Lists / Graphs
- ◆ Hyper-cubes

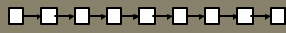
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Arrays




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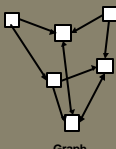
Lists / Graphs



List



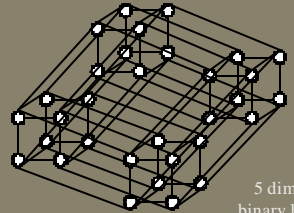
Tree



Graph

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Hyper-Cubes



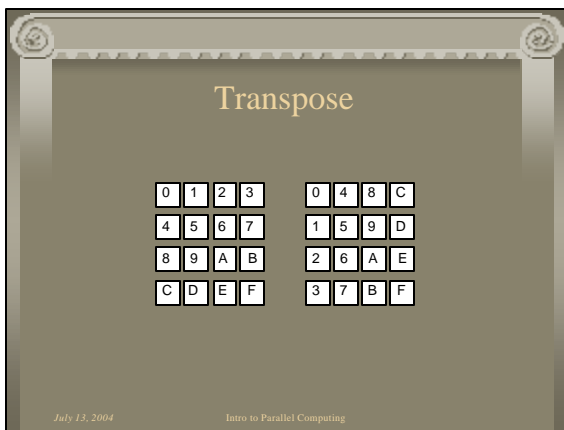
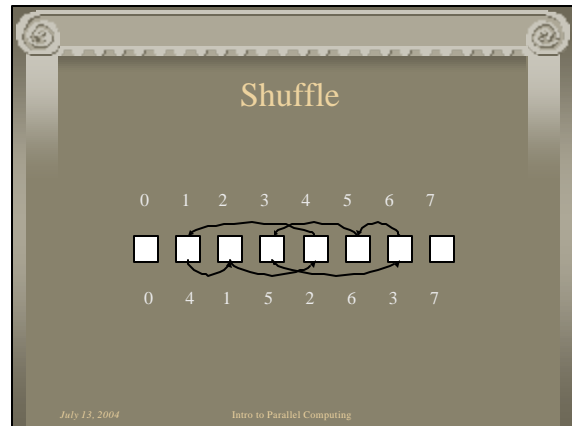
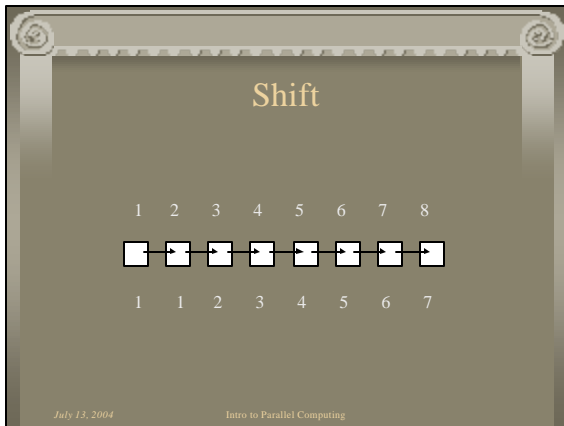
5 dimensional
binary hyper-cube

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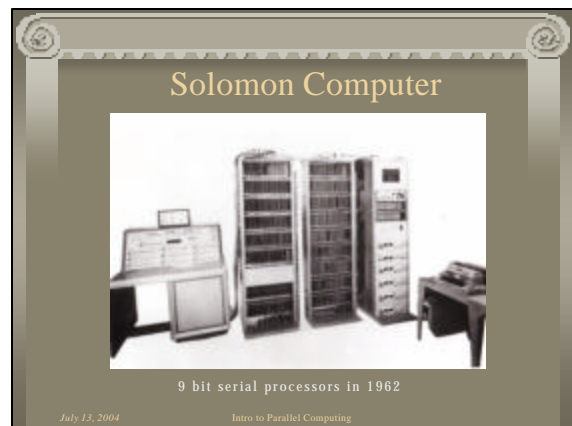
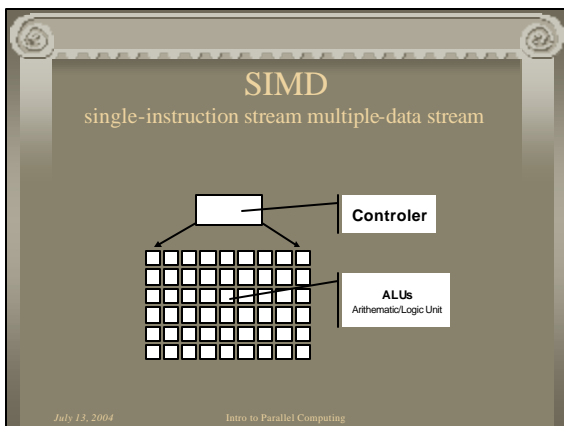
Permutations

- ◆ Shift
- ◆ Shuffle
- ◆ Transpose


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- ## Parallel Architectures
- ✦ SIMD
 - ✦ Pipeline
 - ✦ MIMD
 - ✦ SMP / shared
 - ✦ NUMA / distributive shared
 - ✦ Clusters / distributive
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NASA/Goodyear MPP



16,384 proc
1024 bits/proc

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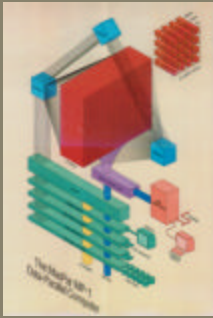
MasPar MP1/MP2



1990-2000
16K custom proc.
\$1.5-2 Million
6.2 GFlop
3.7 sustained (PPM)

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SIMD architecture



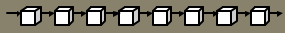
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Present Day SIMD

- ✦ Pentium MMX
- ✦ FPGA architectures

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Pipeline

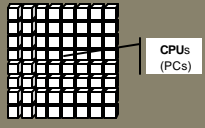


- ✦ Numeric pipeline
 - ✦ Cray
 - ✦ Multiplier
- ✦ Functional pipeline
 - ✦ Pentium /Athlon

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MIMD

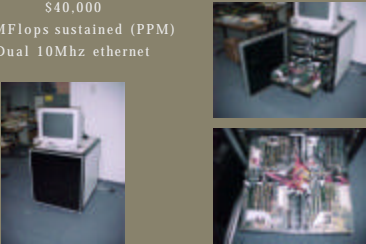
multiple-instruction stream multiple-data stream



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Beowulf I: Wiglaf

1994
16 - 100Mhz 486DX4
\$40,000
50 MFlops sustained (PPM)
Dual 10Mhz ethernet

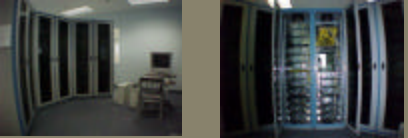


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theHIVE

Highly-Parallel Integrate Virtual Environment


1997	1999
128 - 200Mhz Pentium Pro	128 - 200Mhz Pentium Pro
\$210,000	100Mhz switched ethernet
7.5 Gflops sustained (PPM)	72 port switch
100Mhz switched ethernet	



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Thunderhead

Fall 2002



2.4 Ghz P4 Xeon cluster
1 console node
3 host nodes
256 dual P4 compute nodes
8 dual P4 spare nodes
Fast ethernet
2 Gbit Myrinet

106th on the TOP500 List Nov. 2003

Characteristics:
peak of 2.5 TF
1.1Tflop on LINPAK benchmark
20 TB scratch storage
12.8 TB RAIDed storage

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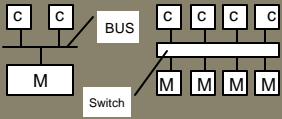
MIMD Architectures

- ◆ SMP / shared
- ◆ NUMA / distributive shared
- ◆ Clusters / distributive

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SMP

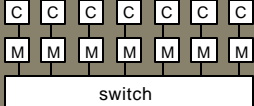
symmetric multi-processor



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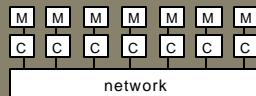
NUMA

non-uniform memory access



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Cluster distributed memory



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Parallel Computing Issues

- ✦ Communication
 - ✦ Bandwidth
 - ✦ Latency
 - ✦ Buffering
- ✦ Computation
 - ✦ Determinism
 - ✦ Race Conditions
 - ✦ Dead lock

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Bandwidth

- ✦ Lower bandwidth
 - higher communication time

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Latency

- ✦ 1. The portion of the communication time not proportional to the message size.
- ✦ 2. The time it takes to send a message.
 - ✦ Latency hiding

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Buffering Issues

- ✦ Memory Copying
 - ✦ Costly in any architecture
- ✦ Double buffering
 - ✦ When viable double buffering can be used to hide communication cost by allowing computations to be performed during communication.

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Determinism

- ✦ Types
 - ✦ Non-deterministic
 - ✦ Deterministic
 - ✦ Ordered
- ✦ Effected Operations
 - ✦ Floating point Multiply and Add
 - ✦ Results consistency and reproducibility
 - ✦ Debugging

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Race Condition

- ✦ Read buffer before data was written to it.
- ✦ Writing to a buffer before it has been read
- ✦ Writing to variables in the wrong order

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Deadlock

- ✦ Two or more processes requesting the same set of resources that are then distributed among processes
- ✦ Two processes sending to each other, causing both to wait for the other to receive

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Synchronize

- ✦ Barriers
- ✦ Blocking/Non-blocking

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Barrier

- ✦ A point during execution where all relevant processes or threads must wait for each other.

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Blocking / Non-Blocking

- ✦ Blocking communications
 - ✦ Communications that does not return until it has completed
- ✦ Non-blocking communications
 - ✦ Communication operation that returns before it is complete
 - ✦ Allows computation to be performed while operation is being performed

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Non-synchronize

- ✦ Mutual Exclusion (critical sections)
 - ✦ Monitor
 - ✦ Semaphores (P/V)
 - ✦ Test and Set

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Monitor

- ✦ Begin monitor
 - ✦ <critical section>
- ✦ End monitor

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PV Semaphore

- ✦ *Dijkstra – counting semaphore*
- ✦ *Proberen te verlangen* (wait) [P]
 - ✦ If semaphore > 0, perform critical section
 - ✦ If semaphore ≤ 0, wait until semaphore > 0
 - ✦ decrement semaphore
- ✦ *verhogen* (post) to increase a semaphore [V]
 - ✦ increment semaphore

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PV Semaphore

- ✦ declare sema4
- ✦ det sema4 = 1
- ✦ P(sema4)
 - ✦ <critical section>
- ✦ V(sema4)

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Binary Semaphore

- ✦ declare sema4
- ✦ lock(sema4)
 - ✦ <critical section>
- ✦ unlock(sema4)

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Test and Set

- ✦ Atomic operation
 - ✦ Test variable
 - ✦ Set variable to TRUE
- ✦ Restrict access during:
 - ✦ interruptible code
 - ✦ multi-processor shared memory system

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Performance Metrics

- ✦ Floating point operations per sec (flops)
- ✦ Time to completion
- ✦ Speed up
- ✦ Efficiency

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FLOPS

- Why is flops a legitimate metric
 - Usually floating point values and operations represent work necessary to solve problem
 - Usually integer operations represent the control of an algorithm
 - The solution of a problem is not necessarily dependent on a specific algorithm

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Time to completion

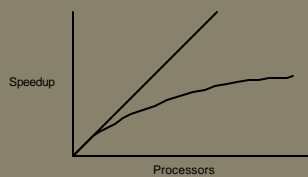
- Why is “time to completion” not a good metric.
 - It is little use to any one but the writer of the algorithm.
 - It depends on a fixed size problem.

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Speed Up

$$Speedup = \frac{Time_for_1}{Time_for_n}$$

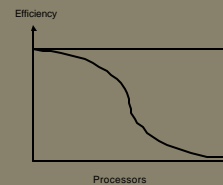


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Efficiency

$$Efficiency = \frac{Speedup}{N}$$



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Performance Issues

- Amdahl's Law
- Latency/Bandwidth
- Computation/Communication

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Amdahl's Law

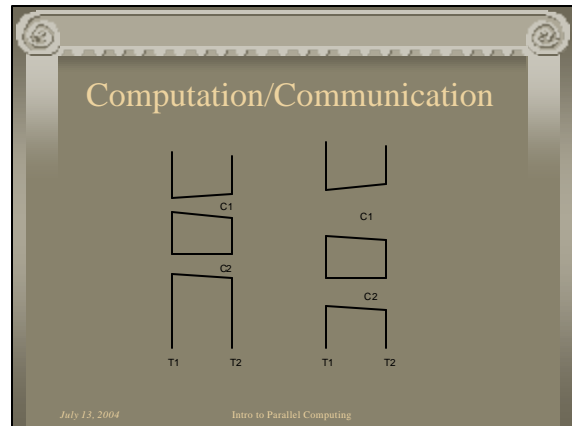
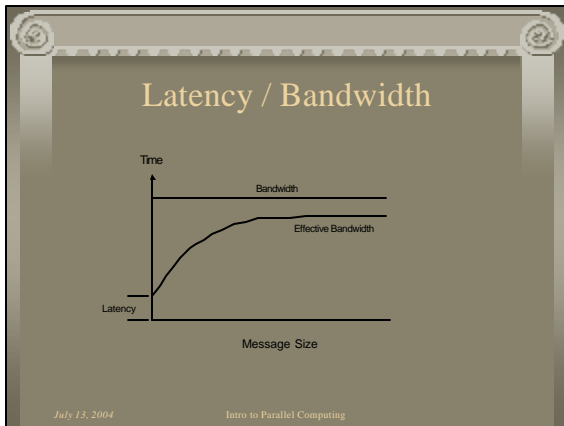
$$T_N = \frac{(1-f)T_1}{N} + fT_1$$

$$Speedup = \frac{N}{(1-f) + Nf} \leq \frac{1}{f}$$

$$Efficiency = \frac{1}{(1-f) + Nf} \leq \frac{1}{fN}$$

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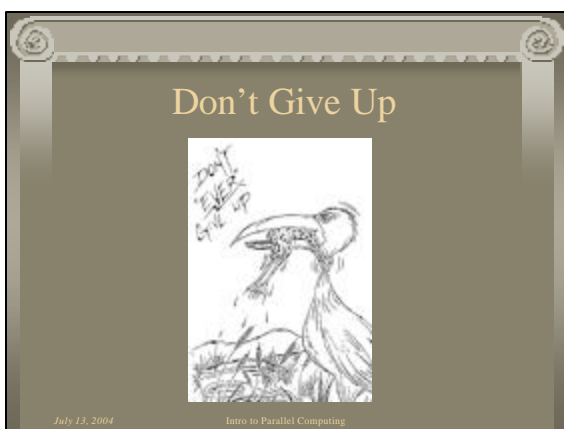


Final words of Wisdom

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!! Think Parallel !!

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Questions?

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